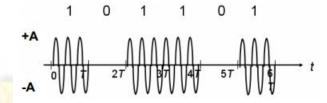


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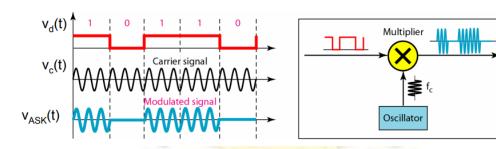
ASK – strength of carrier signal is varied to represent binary 1 or 0

- both frequency & phase remain constant while amplitude changes
- commonly, one of the amplitudes is zero

$$s(t) = \begin{cases} A_0 \cos(2\pi f_c t), & binary \ 0 \\ A_1 \cos(2\pi f_c t), & binary \ 1 \end{cases}$$



- demodulation: only the presence or absence of a sinusoid in a given time interval needs to be determined
 - advantage: simplicity
- disadvantage: ASK is very susceptible to noise interference noise usually (only) affects the amplitude, therefore ASK is the modulation technique most affected by noise
 - application: ASK is used to transmit digital data over optical fiber

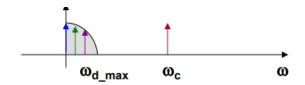


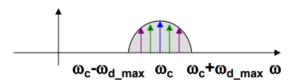
Carrier signal: $v_c(t) = \cos(2\pi f_c t) = \cos(w_c t)$

Digital signal:
$$v_d(t) = A \left[\frac{1}{2} + \frac{2}{\pi} \cos(w_0 t) - \frac{2}{3\pi} \cos(3w_0 t) + \frac{2}{5\pi} \cos(5w_0 t) - \cdots \right]$$

1

Modulated signal $v_{ASK}(t) = v_c(t) \cdot v_d(t) = \frac{1}{2}\cos(w_0 t) + \frac{1}{\pi}[\cos(w_c - w_0)t + \cos(w_c + w_0)t] - \frac{1}{3\pi}[\cos(w_c - 3w_0)t + \cos(w_c + 3w_0)t]$







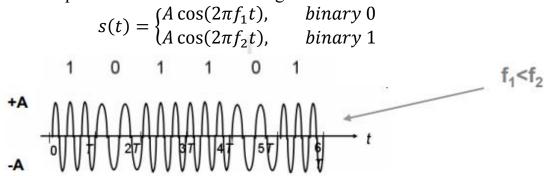
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Example

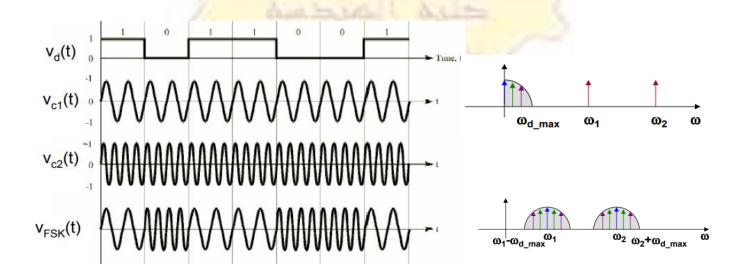
Determine the minimum bandwidth necessary to pass a 10 kbps binary signal using amplitude shift keying.

FSK – frequency of carrier signal is varied to represent binary 1 or 0

• peak amplitude & phase remain constant during each bit interval



- demodulation: demodulator must be able to determine which of two possible frequencies is present at a given time
- advantage: FSK is less susceptible to errors than ASK receiver looks for specific frequency changes over a number of intervals, so voltage (noise) spikes can be ignored
 - disadvantage: FSK spectrum is 2 x ASK spectrum
 - application: over voice lines, in high-freq. radio transmission, etc.





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Digital signal: $v_d(t)$ modulated with w_1 v_d /(t) modulated with w_2

Modulated signal:
$$v_{FSK}(t) = \cos w_1 t. v_d(t) + \cos w_2 t. \left(1 - v_d(t)\right) = \frac{1}{2} \cos w_1 t. + \frac{1}{\pi} \left[\cos(w_1 - w_0)t + \cos(w_1 + w_0)t\right] - \frac{1}{3\pi} \left[\cos(w_1 - 3w_0)t + \cos(w_1 + 3w_0)t\right] + \dots + \frac{1}{2} \cos w_2 t. - \frac{1}{\pi} \left[\cos(w_2 - w_0)t + \cos(w_2 + w_0)t\right] + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right] + \dots + \frac{1}{3\pi} \left[\cos(w_2 - 3w_0)t + \cos(w_2 + w_0)t\right$$

Example

Determine (a) the peak frequency deviation, (b) minimum bandwidth, and (c) baud for a binary FSK signal with a mark frequency of 49 kHz, a space frequency of 51 kHz, and an input bit rate of 2 kbps.

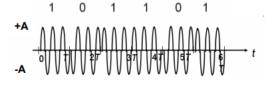
PSK – phase of carrier signal is varied to represent binary 1 or 0

- peak amplitude & freq. remain constant during each bit interval
- example: binary $1 = 0^{\circ}$ phase, binary $0 = 180^{\circ}$ (π rad) phase
- ⇒ PSK is equivalent to multiplying carrier signal by +1 when the information is 1, and by -1 when the information is 0

Binary PSK, since only 2 different phases

$$\begin{split} s(t) = & \begin{cases} Acos(2\pi f_c t), & \text{binary 1} \\ Acos(2\pi f_c t + \pi), & \text{binary 0} \end{cases} \\ s(t) = & \begin{cases} Acos(2\pi f_c t), & \text{binary 1} \\ -Acos(2\pi f_c t), & \text{binary 0} \end{cases} \end{split}$$

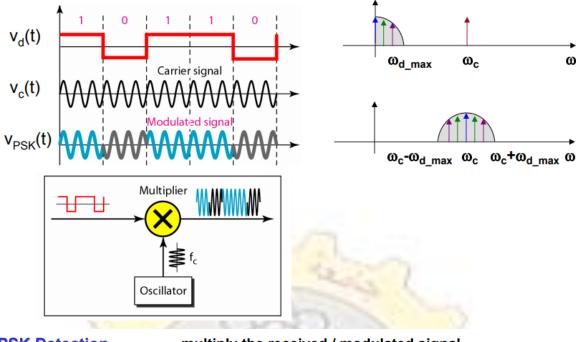
$$s(t) = \begin{cases} A\cos(2\pi f_c t), & \text{binary 1} \\ -A\cos(2\pi f_c t), & \text{binary 0} \end{cases}$$



- demodulation: demodulator must determine the phase of received sinusoid with respect to some reference phase
- advantage: f PSK is less susceptible to errors than ASK, while it requires/occupies the same bandwidth as ASK f more efficient use of bandwidth (higher data-rate) are possible, compared to FSK!!!
 - disadvantage: more complex signal detection / recovery process, than in ASK and FSK



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PSK Detection – multiply t + Acos(2

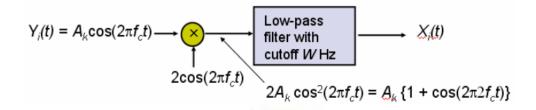
$$\cos^2 A = \frac{1}{2} (1 + \cos 2A)$$

- multiply the received / modulated signal $\pm A\cos(2\pi f_c t)$ by $\frac{2*\cos(2\pi f_c t)}{2}$
 - resulting signal

$$2A\cos^2(2\pi f_c t) = A[1 + \cos(\frac{4\pi f_c t}{4\pi f_c t})], \text{ binary 1}$$

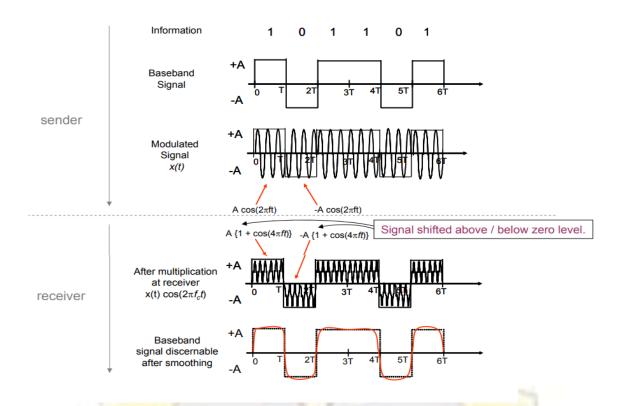
$$-2A\cos^2(2\pi f_c t) = -A[1+\cos(4\pi f_o t)],$$
 binary 0

• by removing the oscillatory part with a low-pass filter, the original baseband signal (i.e. the original binary sequence) can be easily determined

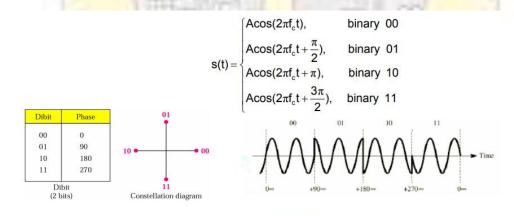




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QPSK = 4 QPSK = 4-PSK – PSK that uses phase shifts of 90°= $\pi/2$ rad \Rightarrow 4 different signals generated, each representing 2 bits



- advantage: higher data rate than in PSK (2 bits per bit interval), while bandwidth occupancy remains the same
 - 4-PSK can easily be extended to 8-PSK, i.e. n-PSK
- however, higher rate PSK schemes are limited by the ability of equipment to distinguish small differences in phase



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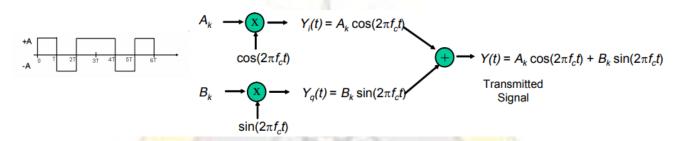
Quadrature Amlitude Modulation – uses two dimentional signalling

 \bullet Original information stream is split into two sequences that consists of odd and even symbols, e.g B_k and A_k

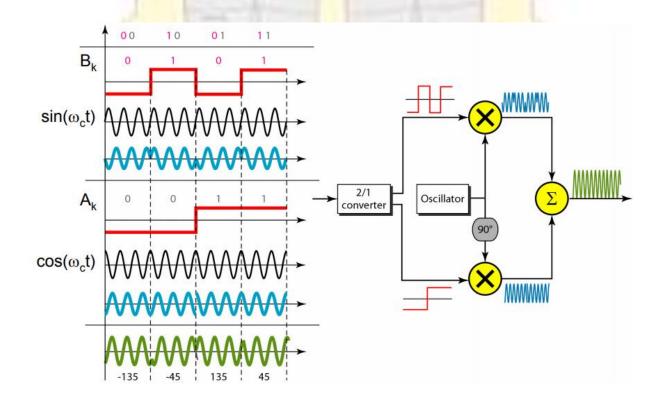
1 1 2 2 3 3

 A_k sequence (in-phase comp.) is modulated by $cos(2\pi f_c t)$ B_k sequence (quadrature-phase comp.) is modulated by $sin(2\pi f_c t)$

Composite signal $A_k \cos(2\pi f_c t) + B_k \sin(2\pi f_c t)$ is sent through the channel



• advantage: data rate = 2 bits per bit-interval!



- **QAM Demodulation** by multiplying Y(t) by $2 \cdot cos(2\pi f_c t)$ and then lowpass filtering the resultant signal, sequence A_k is obtained
 - by multiplying Y(t) by $2 \cdot \sin(2\pi f_c t)$ and then lowpass filtering the resultant signal, sequence Bk is obtained

